Writing an FAC Solver

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Introduction

The SAMRAI library provides high-level abstractions for writing linear equation solvers using on the fast adaptive composite (FAC) algorithm. The FAC algorithm and all operations common to it are provided in the class `solv_FACPreconditionerX`, while problem-specific operations are accessed through the interface of the abstract `solv_FACOperatorStrategyX` class.

Thus, `solv_FACPreconditionerX`

- provides the entry point for the solution process.
- controls the FAC cycles and parameters such as number of cycles, residual tolerance, and number of smoothing sweeps
- provide temporary storage for error and residual vectors.

The `solv_FACOperatorStrategyX` class provides interfaces to these problem-specific operations:

- restricting the solution
- restricting the residual
- prolonging the error and applying the correction
- solving the coarsest level
- computing the residual norm

These operations require the details of the equation and discretization methods and must be implemented in the a concrete child class.

To develop a solver using the FAC algorithm, one uses a combination of the preconditioner and a concrete implementation of the operator strategy abstract class. This document describes the methods contained in these two classes, how to implement `solv_FACOperatorStrategyX` and how to use the preconditioner. For an example of an FAC operator class, see `solv_CellPoissonFACOpsX`. For an example of using the preconditioner, see the higher-level class `solv_CellPoissonFACSolverX`.

Using `solv_FACPreconditionerX`

This section covers the setup and usage of the preconditioner. For users of the solver, this is the most important part. The operator strategy methods are called through the FAC preconditioner class. Each preconditioner object requires one operator strategy implementation, which is registered through the preconditioner's constructor. This section covers the basic usage of the preconditioner, which involves setting up the parameters, initiating the solve and getting information on the solution process.

Setting up the preconditioner parameters involves these preconditioner methods and corresponding input parameters:

Method	***Input name***	***Default setting***
`setPresmoothingSweeps(int num_pre_sweeps)`	`num_pre_sweeps`	`1`
`setPostsmoothingSweeps(int num_post_sweeps)`	`num_post_sweeps`	`1`
`setMaxCycles(int max_cycles)`	`max_cycles`	`10`
`setResidualTolerance(double residual_tol)`	`residual_tol`	`1.00E-006`
`enableLogging(bool enable)`	`enable_logging`	`FALSE`

These simple functions are self-explanatory.

The method

```
solveSystem(solv_SAMRAIVectorRealX<double> &u,
            solv_SAMRAIVectorRealX<double> &f);
```

performs the solve. The unknown u and right-hand-side f are described as vectors so that systems of equations are handled through the same interface. Vectors can wrap multiple patch data under a single object. The two vectors must have the same hierarchy, level range and number of components. Further requirements, such as ghost cell width, may be imposed by the operator object. The method `solveSystem` initializes the solver state (set up temporary storage, etc.), performs the FAC cycling steps according to the above parameters, then deallocate the solver state. For multiple solves, the solver state can be set up and preserved through out the solve, leading to significant time savings. The methods

```
void initializeSolverState(
   const solv_SAMRAIVectorRealX<double> &solution ,
   const solv_SAMRAIVectorRealX<double> &rhs );
```

and

```
void deallocateSolverState();
```

are used set up and remove the solver state manually. If `solveSystem` is entered with an initialized state, that state will be used but left undisturbed. Otherwise, the state is initialized using the vector arguments to `solveSystem`. Note that `initializeSolverState` or `deallocateSolverState` call corresponding functions in the FAC operator object (described below) to keep that object in a matching state.

After a solve, the number of FAC iterations, the residual norm and the convergence factors can be retrieved by the functions

```
int getNumberIterations() const
void getConvergenceFactors(double *avg_factor,
                           double *final_factor) const
double getResidualNorm() const
```

The convergence factor is the factor by which the residual is reduced by one FAC iteration. The average factor is that which, when applied the number of iterations used gives the same overall reduction, while the final factor is that of the last iteration taken. The residual norm is the RMS norm of the residual.

Implementing `solv_FACOperatorStrategyX`

Critical methods that must be implemented in `solv_FACOperatorStrategyX` are the pure virtual functions performing essential operations for the FAC solver.

- `restrictSolution`
- `restrictResidual`
- `prolongErrorAndCorrect`
- `smoothError`
- `solveCoarsestLevel`
- `computeCompositeResidualOnLevel`
- `computeResidualNorm`

In addition, there are three non-pure virtual functions that are not related to the FAC algorithm but help in the implementation of the strategy class:

- `initializeOperatorState`
- `deallocateOperatorState`
- `postprocessOneCycle`

This section will make general comments about these methods. The source code documentation of this abstract class provides the full description, requirement and allowable assumptions when implementing the methods.

As with the solv_FACPreconditionerX class, patch data are represented through vectors. It is important to know that the vectors are those given to `initializeOperatorState`, those given to `solv_FACPreconditionerX::solveSystem` or clones of those vectors, leading to some consistency through out the FAC solve.

Each of the essential operations for the FAC solver, with the exception of `computeResidualNorm`, operates on just one level. The level number argument in these functions always refers to the level whose data is being changed. The restrict and prolong operations obviously require data from an adjacent level, but they modify only one level. For methods that require data from an adjacent level, you can make certain assumptions about the state of the data in the adjacent level, and are required to prepare data that may subsequently be used. This is due to the fact that these functions are only called at appropriate points in the logical sequence of steps performed in an FAC cycle.

The computation of the residual norm by `computeResidualNorm` should only compute the norm of the data passed in. It should not recompute the residual, which is done by `computeCompositeResidualOnLevel`.

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