

Resource Partitioning and Power Management in the Exascale Era



ANL: Swann Perarnau, Idriss Daoudi, Kamil Iskra, Kazutomo Yoshii, John-Luke Navarro, Pete Beckman LLNL: Tapasya Patki, Stephanie Brink, Aniruddha Marathe, Barry Rountree University of Arizona: David Lowenthal and team

Improving all layers of the open-source resource management ecosystem

The goal of the Argo resource management effort is to provide user-facing advanced mechanisms to control and monitor resource usage across the system. This includes performance isolation, support for advanced workloads such as workflows and coupled-codes, and comprehensive power management.

Local (Node) Resource Management

Overview

- Hierarchical resource partitioning
- Containers for intra-node resource partitioning
 - Using the cgroups mechanism of Linux
- More efficient "packing" of multi-component applications
- Arbitrate resources between applications and runtime

Global Power Management

Scheduler-Aware Hierarchical Control

- Integrate job scheduler, enclaves to control power across jobs
- Use NRM data to monitor power and application performance
- Steer power where it can most advance the application's progress
- ECP goals: production-ready GRM, integration across different
- services
- Reconfigurable, dynamically tracking resource changes
- Integration with batch schedulers, power management

Node Resource Manager

- Single API endpoint for all node resource management services
- Map containers to topology, interact with container runtime
- Pub/Sub API to control, measurements events
- RPC API: user access to container management, control loop configuration, actuators
- Goals: integration across hierarchy levels, collaboration with job schedulers, MPI

Sensors, Actuators, and Configurable Control

NRM performs abstracted resource accounting in the form of "sensors" and "actuators", allowing for flexible control design.

- Monitor application and hardware through multiple APIs: self-reporting progress, PMPI, hardware performance counters
- Actuators act on hardware/application through resource arbitration layer: RAPL, control groups, signals
- Control loop is expressed as a function of available sensors, actuators, and user-defined goal.
- Specified through a Control Problem Description format
- Currently synthesizes a Multi-Armed Bandit controller • ECP goals: improve control loop, integrate more sensor data into policies, better sensor data management



- **PowerStack**: Developed first prototype with SLURM, GEOPM and Variorum to lead community effort toward capturing power management details from the microarchitecture-level up to the site-level.
- PowerStack continues to bring together industrial partners as part of CRADA effort and active collaborations with vendors (HPE, ARM, Intel, AMD, IBM and NVIDIA).





Variorum Latest Features

- https://variorum.readthedocs.io
- Extensible, open-source library for exposing low-level hardware knobs and vendor-neutral API for power management • Adds support for AMD (under NDA), allowing for 4 platforms and 10 microarchitectures to be supported. Extends JSON-based API support for interaction with other system software components. Additionally, integration with Kokkos, Flux, and Caliper has been implemented.



Reconfigurable, Application-Specific Control Loop



NRM Latest Features

- https://nrm.readthedocs.io
- Added scope (topology information) to sensor data, to map monitoring position to actuators granularity
- Support for OMPT, variorum, PAPI as sensor providers

Evaluation of Nvidia and AMD GPU Power Knobs

- **Objective:** Investigate available methods for power management on GPUs from different vendors
- **Test Platforms:** MI50 and MI60 AMD GPUs on Corona system, Volta GPUs on Lassen system at LLNL
- **Results:** Observed interesting power, frequency and thermal tradeoffs with different benchmarks



Lawrence Livermore National Laboratory



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